Université d'Ottawa Faculté de génie Département de

génie mécanique



University of Ottawa Faculty of Engineering

Department of Mechanical Engineering

MCG 3307: Control Systems II

Winter 2013

Instructor: Dr. Davide Spinello email: dspinell@uottawa.ca

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office hours: Take an appointment by email

Lectures: MCD 121 MondaY 14:30 - 16:00 Thursday 16:00 - 17:30

Tutorial: STE 0130 (computer room), Friday 8:00 - 10:00

Textbook: two editions (fourth and fifth) of the textbook (see below) are allowed. For the rest of the syllabus the two editions will be distinguished by enclosing between square brackets entities referred to the fourth edition (for example "Ch. 6" will be referred to the fifth edition, whereas "[Ch. 6]" will be referred to the fourth edition).

Ogata, K.: Modern control engineering - Fifth edition. Prentice Hall, 2009 Ogata, K.: Modern control engineering - Fourth edition. Prentice Hall, 2001

Web page: http://by.genie.uottawa.ca/~spinello/webpage/teaching.html

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Course Outline

Systems response analysis: Chapter 5

General structure of controllers; First order systems; Higher order systems; Routh's stability criterion; Integral and derivative control actions: effects on systems performance; Steady-state errors.

Root-locus method: Chapter 6 [Chapters 6 and 7]

The concept of root-locus; Rules for constructing root-loci; Root-locus analysis of control systems; Control-systems design by the root-locus approach.

Frequency-response method: Chapter 7 [Chapters 8 and 9]

Response to sinusoidal inputs; Bode diagrams; Experimental determination of transfer functions; Control-systems design by the frequency-response approach.

Description and objectives

This course presents the concepts of transient and steady-state response analysis for control systems, assess the stability of control systems through the root-locus method and the frequency-response method, and teaches methods for designing controllers that correspond to desired system behaviours. Students will develop the capability of analyzing the stability of a system and of designing simple controllers to regulate systems behaviour.

Exams: policy and dates

All exams will be open book - open notes.

Illegible work and loose sheets will not be graded. If a student cannot attend a test/exam due to a medical condition, certified by a doctor, he/she must notify the instructor in advance. Unexcused absence from an exam will result in a grade of 0 for that exam.

The date of the of the mid-term exam can be changed within the first week of class, according with specific exigences of the students.

Mid-term exam Thu, Feb 14 (During lecture)

Final exam TBD

Computer oriented assignments

Four computer oriented homeworks will be assigned during the term. Assignments will be individual. Students are required to use Matlab and to return the assignments in a report format. There will be tutorial sessions, given in a computer lab, dedicated to problems solving with Matlab.

Marks

Marks from computer oriented assignments and mid-term exam determine the semester mark S, computed as follows:

Mid-term exam	60%
Computer oriented assignments	40%
Total of semester (S)	100%

This mark will be combined with the final exam mark F in the following way:

0.6F + 0.4S

If F < 55%, regardless of the mark of the semester S the overall course grade will be F.

Regulations on Academic Fraud

The following link provides information regarding academic fraud, including the Regulation on Academic Fraud which provides information on the definition of fraud, the disciplinary process and the consequences of dishonest behaviour: http://web5.uottawa.ca/mcs-smc/academicintegrity/regulation.php

Suggested problems

5th edition

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{\it Chapter 5: B-5-2, B-5-5, B-5-8, B-5-20, B-5-21, B-5-23, B-5-27, B-5-28}
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Chapter 6: B-6-1, B-6-3, B-6-4, B-6-6, B-6-10, B-6-15, B-6-18, B-6-19, B-6-20, B-6-23, B-6-26

Chapter 7: B-7-2, B-7-5, B-7-9, B-7-11, B-7-23, B-7-26, B-7-30, B-7-32, B-7-34

4th edition

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Chapter 5: B-5-2, B-5-6, B-5-10, B-5-23, B-5-25, B-5-27, B-5-31, B-5-32
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Chapter 6: B-6-1, B-6-4, B-6-6, B-6-9, B-6-14

Chapter 7: B-7-7, B-7-10, B-7-11, B-7-12, B-7-16, B-7-20

Chapter 8: B-8-2, B-8-6, B-8-11, B-8-13, B-8-26, B-8-29

Chapter 9: B-9-2, B-9-5, B-9-9

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Lecture	Reading	Topic	
1: Mo, Jan 7	5-1; 5-2; 5-3 [5-1; 5-2; 5-3]	Course introduction and overview; First and second order systems	
2: Th, Jan 10	5-3 [5-3]	Second order systems	
3: Mo, Jan 14	5-4; 5-6 [5-4; 5-6]	Higher order systems; Routh's stability criterion	
4: Th, Jan 17	5-6; 5-7 [5-6; 5-7]	Routh's stability criterion; System performance: effects of integral	
		and derivative control actions	
5: Mo, Jan 21	5-7 [5-7]	System performance: effects of integral and derivative control ac-	
		tions	
6: Th, Jan 24	5-8 [5-8]	Steady-state errors in unity-feedback control systems	
7: Mo, Jan 28	6-1; 6-2 [6-1; 6-2]	The concept of root-locus; Root-locus plots	
8: Th, Jan 31	6-2 [6-2; 6-3]	Root-locus plots; Gain selection with root-locus plots	
9: Tu, Feb 4 6-4; 6-5	[6-5; 7-1; 7-2]	Root-locus plots of positive feedback systems; Control-systems de-	
		sign by the root-locus approach	
10: Th, Feb 7	6-6 [7-3]	Lead compensation	
11: Mo, Feb 11	6-7 [7-4]	Lag compensation	
12: Th, Feb 14		$\mathbf{Mid}\text{-}\mathbf{term}\ \mathbf{exam}^1$	
Feb 17 - Feb 23		Study week	
13: Mo, Feb 25	6-8; 6-9 [7-5; 7-6]	Lag-lead compensation; Parallel compensation	
14: Th, Feb 28	7-1 [8-1]	Systems output to sinusoidal inputs	
15: Mo, Mar 4	7-2 [8-2]	Systems output to sinusoidal inputs; Bode diagrams	
16: Th, Mar 7	7-2 [8-2]	Bode diagrams	
17: Mo, Mar 11	7-2 [8-2]	Bode diagrams; The resonant frequency	
18: Th, Mar 14	7-2 [8-2]	General procedure to plot Bode diagrams; Minimum phase systems	
		and Nonminimum phase systems; Transport Lag	
19: Mo, Mar 18	7-2; [8-2]	Determination of static error constants with Bode diagrams; Ex-	
		amples	
20: Th, Mar 21	7-9 [8-11]	Experimental determination of transfer functions	
21: Mo, Mar 25	7-7 [8-9]	Relative stability: Phase and gain margins, Phase and Gain	
00 551 15 00	- 40 - 44 [0 4 0 0]	crossover frequencies; Cutoff frequency and bandwidth; Cutoff rate	
22: Th, Mar 28	7-10; 7-11 [9-1; 9-2]	Control systems design by frequency-response approach; Lead com-	
00 757 4 4	- 40 - 44 [0 4 0 0]	pensation	
23: Th, Apr 4	7-10; 7-11 [9-1; 9-2]	Control systems design by frequency-response approach; Lead com-	
OF TO A O	7 10 [0 0]	pensation	
25: Tu, Apr 9	7-12 [9-3]	Lag compensation	

¹ The midterm exam will cover topics lectured up to lecture 11 (remind: this is a *tentative* lecture schedule).