

Last updated: Wednesday 13 April, 2016



Faculty of Engineering
Department of Mechanical Engineering

CONTROL SYSTEMS
MCG3307A
Davide Spinello
Winter 2016

Course Hours

Monday 14:30 - 16:00

Location: CBY-D207

Type: LEC 1

Thursday 16:00 - 17:30

Location: CBY-D207

Type: LEC 2

Friday 08:00 - 10:00

Location: CBY-B02

Type: TUT 1

Professor

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Office Hours

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Location: Appointment by email

Teaching Assistant

Farhad Mir Hosseini (fmirh084@uOttawa.ca)

Phone Number: --

Office Hours

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Location: Appointment by email

Gagandeep Singh (gsing031@uOttawa.ca)

Phone Number: --

Office Hours

Friday 10:00 - 14:00

Location: CBY B08D desk #7

Course Description

Feedback theory. Time and frequency domain analysis of feedback control systems. Stability criteria. Design of simple feedback control systems and compensation techniques. Statespace analysis of

systems. Laboratory experiments.

General and Specific Objectives

This course presents the concepts of transient and steady-state response analysis for control systems, assess the stability of control systems, and teaches methods for designing controllers that correspond to desired system behaviours. Students will develop the capability of analyzing the stability of a system and of designing simple controllers to regulate systems behaviour.

Required Material

The textbook in the Section "Monographies" is mandatory. In the course calendar, sections of the book that cover lectures' material are referenced by numbers in square brackets.

Evaluations

Problem Set

Evaluation Date: Ongoing

Evaluation Percentage: 16

The homework assignments are individual and they are instrumental to prepare for exams, as they cover in an advanced way topics addressed in class. There are 4 assignments during the term, each weighting 4% of the final grade.

Written exam (e.g. exam, long answer)

Evaluation Date: Monday 22 February, 2016

Evaluation Percentage: 24

Midterm exam. The exam is in class, open book and open notes. Electronic devices are not allowed. The exam covers the material developed in class up to Lecture 10. For additional information, see the course calendar.

Written exam (e.g. exam, long answer)

Evaluation Date: Saturday 16 April, 2016

Evaluation Percentage: 60

Final exam: MRT 218. The exam is open book and open notes. Electronic devices are not allowed. The exam will may cover all material developed in class.

Course Calendar

Monday 11 January, 2016	Lecture 1 <ul style="list-style-type: none">• Course introduction and overview.• Stability of higher order systems [5-4].
Wednesday 13 January, 2016	Lecture 2 <ul style="list-style-type: none">• Routh's stability criterion [5-6].
Monday 18 January, 2016	Lecture 3 <ul style="list-style-type: none">• Routh's stability criterion [5-6].

Wednesday 20 January, 2016	Lecture 4 • System performance: effect of derivative and integral control actions [5-7].
Monday 25 January, 2016	Lecture 5 • Steady-state errors in unity-feedback control systems [5-8].
Wednesday 27 January, 2016	Lecture 6 • Steady-state errors in unity-feedback control systems [5-8].
Monday 1 February, 2016	Lecture 7 • The concept of root-locus; root-locus plots [6-1, 6-2].
Thursday 4 February, 2016	Lecture 8 • Root-locus plots [6-1, 6-2].
Monday 8 February, 2016	Lecture 9 • Root-locus plots; gain selection with root-locus plots [6-1; 6-2].
Thursday 11 February, 2016	Lecture 10 • Root-locus plots; gain selection with root-locus plots [6-1; 6-2].
Monday 22 February, 2016	Lecture 11 • Midterm exam.
Thursday 25 February, 2016	Lecture 12 • Control systems design by the root locus approach [6-5]. • Lead compensation [6-6].
Monday 29 February, 2016	Lecture 13 • Lag compensation [6-7].
Thursday 3 March, 2016	Lecture 14 • --
Monday 7 March, 2016	Lecture 15 • System output to sinusoidal inputs [7-1].
Thursday 10 March, 2016	Lecture 16 • Bode diagrams [7-2].
Monday 14 March, 2016	Lecture 17 • Bode diagrams; resonant behaviour [7-2].
Thursday 17 March, 2016	Lecture 18 • General procedure to plot Bode diagrams; Minimum phase and non-minimum phase systems; Transport lag [7-2].
Monday 21 March, 2016	Lecture 19 • Experimental determination of transfer functions [7-9].
Thursday 24 March, 2016	Lecture 20 • Control system analysis in state-space. State-space representations [9-2].
Thursday 31 March, 2016	Lecture 21 • Solving time-invariant state equations [9-4]. • Controllability [9-6].
Monday 4 April, 2016	Lecture 22 • Control systems design in state space. • Pole placement [10-2].
Thursday 7 April, 2016	Lecture 23 • Quadratic optimal regulator system [10-8].
Monday 11 April, 2016	Lecture 24 • Observability [9-7]. • State observers [10-5].

Other Information

- At the beginning of the course the students are assumed to be familiar with the theory of ordinary differential equations, Laplace transforms, Fourier transforms, basic complex numbers algebra, and most importantly with material covered in MCG3305 and MCG3306. You are strongly encouraged to review the related material from pre-requisite courses.
- Suggested problems:
 - **Chapter 5:** B-5-2, B-5-5, B-5-8, B-5-20, B-5-21, B-5-23, B-5-27, B-5-28.
 - **Chapter 6:** B-6-1, B-6-3, B-6-4, B-6-6, B-6-10, B-6-15, B-6-18, B-6-19, B-6-20, B-6-23, B-6-26.
 - **Chapter 7:** B-7-2, B-7-5, B-7-9, B-7-11, B-7-23, B-7-26, B-7-30, B-7-32, B-7-34.
 - **Chapter 9:** B-9-3, B-9-4, B-9-5, B-9-7, B-9-10, B-9-11.
 - **Chapter 10:** B-10-3, B-10-4, B-10-5, B-10-6, B-10-7, B-10-9, B-10-17, B-10-19.

Monographs

Ogata, K.: *Modern control engineering - Fifth edition*. Prentice Hall, 2009.

Plagiarism

Beware of academic fraud!

Academic fraud is an act by a student that may result in a false evaluation (including papers, tests, examinations, etc.). It is not tolerated by the University. Any person found guilty of academic fraud will be subject to severe sanctions.

Here are some examples of academic fraud:

- Plagiarism or cheating of any kind;
- Present research data that has been falsified;
- Submit a work for which you are not the author, in whole or part;
- Submit the same piece of work for more than one course without the written consent of the professors concerned.

Please consult [this webpage](#): it contains regulations and tool to help you avoid plagiarism. An individual who commits or attempts to commit academic fraud, or who is an accomplice, will be penalized. Here are some examples of possible sanctions:

- Receive an “F” for the work or in the course in question;
- Imposition of additional requirements (from 3 to 30 credits) to the program of study;
- Suspension or expulsion from the Faculty.

You can refer to the regulations on [this webpage](#).

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- Expand your critical thinking abilities
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- Learn what the expectations are for academic writing

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